# Kim, Chi Yen



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#### Resume

I was a assistant professor in Yeungnam College of Science & Technology and now works as Research Assistant Professor at Mechanical Engineering &W.M. Keck center for 3D Innovation in UTEP from April 1 2013. I have graduated from B.S to Ph.D at the school of mechanical engineering in Pusan National University and majored in control and measuring technologies, robotics and automation. When I worked at companies, SLS Co.Ltd and Tinics Korea Co.Ltd, I developed inspection systems and MILES gear systems. Now I have an interest in and research about the motion control system and dynamics of additive manufacturing process.

More detailed about my experience and career are address as follows;

#### Education

- Ph.D. Intelligent Control and Automation in the School of Mechanical Engineering, Pusan National University, Pusan, Korea Dissertation: *Reaction Force Estimation of Surgical Robot Instrument for Haptic Realization*. Advisors: Dr. Mincheol Lee Date of graduation: February 2013
- M.E. Mechanical and Intelligent System Engineering Pusan National University, Pusan, Korea Master Thesis: Development of a stereo vision system using reference object and relative stereo disparity with subpixel resolution Advisor: Dr. Mincheol Lee Date of graduation: February 2001
- **B.E.** Mechanical Engineering, Pusan National University, Pusan, Korea Date of graduation: February 1996

#### **Work Experience**

11/2016- present Topic organizer and session organizer ASME International mechanical engineering congress & Exposition (IMECE)

04/2013-present	Assistant Research Professor W.M Keck Center for 3D Innovation University of Texas at El Paso
04/2011-03/2013	Assistant Professor Division of Mechanical Engineering Technology Yeungnam College of Science & Technology
04/2008-03/2011	<i>Research Scientist</i> , Advisor: Dr. Mincheol Lee Pusan National University, Research Institute of Mechanical Engineering
12/2007-04/2008	Shorterm Researcher, Advisor: Dr. Ryan Wicker UTEP, W.M. Keck center for 3D Innovation
12/2002-08/2007	Chief manager of R&D group Tinics Korea.Ltd
02/2000-11/2002	Laser and Vision research Group- Researcher SLS Co.ltd

## Membership in Professional Societies

- Member of Institute of Control, Robot, and Systems
- Member of Korea Society of Precision Engineering
- Member of IEEE

## **Research Project**

- <u>AMERICA MAKES: Multi-functional BAAM: Big Area AM with Multi-Purpose</u> <u>Wire Embedding:</u> 2017 – My Contribution : Researcher for manipulation system
- AMERICA MAKES: A Low-cost Industrial Multi3D System for 3D Electronics
  Manufacturing:
  OCT, 2016
  - My Contribution : Researcher for Robotic assisted System Integration
- <u>AMERICA MAKES 3D Printing Multi-Functionality:</u> <u>Additive Manufacturing for Aerospace Applications</u> OCT, 2013 – MAY,2016 My Contribution : Researcher for Robotic assisted System Integration
- Development of Laparoscopic surgical robot system
   Dec, 2007 Nov, 2010
   Sponsor : Ministry of Knowledge Economy
   My Contribution : Member, Dynamic analysis and Control algorithm for surgical robot instrument

  Development of Hybrid LED Advanced Front Fog & DRI
- <u>Development of Hybrid LED Advanced Front Fog & DRL</u> June, 2012 – Present Sponsor : Small & Medium Business Administration and JS Korea Co.Ltd My Contribution : Project Manager, LED lamp Source and Cooling System Design and

**Overall Scheme** 

•	Development	of	mobile	fused	deposition	modeling	system
	Jan,	20	08	_	April,		2008
			. ~ .				

My Contribution : Member, System Integration.

### Publications (Most recent 3 years ) :

- 1. APPARATUS AND METHOD FOR CONFIGURING A VERTICAL INTERCONNECTION ACCESS AND A PAD ON A 3D PRINTED CIRCUIT UTILIZING A PIN, US Patent App. 62/349,908
- 2. METHOD AND APPARATUS FOR WIRE HANDLING AND EMBEDDING ON AND WITHIN 3D PRINTED PARTS, US patent App. 15/244,061
- 3. IN-SITU DIAGNOSTICS AND CONTROL METHOD AND SYSTEM FOR MATERIAL EXTRUSION 3D PRINTING, US Patent APP. 62/330,361
- **4.** A study to detect a material deposition status in fused deposition modeling technology, C Kim, D Espalin, A Cuaron, MA Perez, E MacDonald, RB Wicker, 2015 AIM.
- 5. Sliding perturbation observer based reaction force estimation method of surgical robot instrument for haptic realization, SM Yoon, MC Lee, CY Kim, International Journal of Humanoid Robotics 12(02)
- 6. Cooperative tool path planning for wire embedding on additively manufactured curved surfaces using robot kinematics, C Kim, D Espalin, A Cuaron, MA Perez, M Lee, E MacDonald, RB Wicker, Journal of Mechanisms and Robotics 7 (2)
- 7. A Study on Manufacturing System Integration with a 3D printer based on the Cloud Network, C Kim, D Espaline, E MacDonald, RB Wicker, DH Kim, JH Sung, JW Lee , Journal of the Korean Society of Manufacturing Process Engineers 14 (3)
- 8. **Dynamic modeling of coupled tendon-driven system for surgical robot instrument,** CY Kim, MC Lee, RB Wicker, SM Yoon, International Journal of Precision Engineering and Manufacturing 15(10)

Additional publications are able to be found in google scholar : (https://scholar.google.com/citations?user=ubfcayYAAAAJ&hl=en)

## I hereby declare that the above statement is true and correct in every respect to the best of my knowledge.